

NAVAL POSTGRADUATE SCHOOL

Introduction to PyML

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 - Nora Aftel
 - Patricia Gomez



Python Modeling Library (PyML) Goals

- Lower access barrier to system modeling with opensource tool environment
 - Harness power of extensive Python scientific computing and utility libraries (bootstrap don't reinvent)
- Provide integrated capabilities for systems modeling, analysis, documentation and code generation
 - SysML, other SE model types and analysis methods
- Be digital engineering compliant with single source of truth across model set
- Compatibility of everything on desktop OS's and in cloud



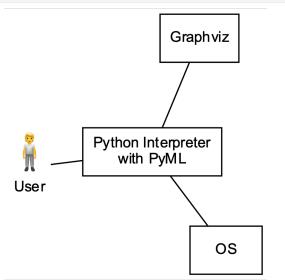
General Usage Features

- Use Python for modeling to intersperse model data, system analysis and documentation
- Model data can be inline code, read from or to external files
- Round-trip engineering to support rapid iterative development
 - Change a model element and all others affected are automatically updated to maintain consistency across model set
 - Automatic document re-generation with all changes
- Inherent configuration management automation
 - All artifacts for a project can be developed and controlled with standard version control system such as GitHub for small to large teams.
 - All models, diagrams, and simulations are specified in text files supporting standard tools for version differencing and reconciliation.

```
import pyml

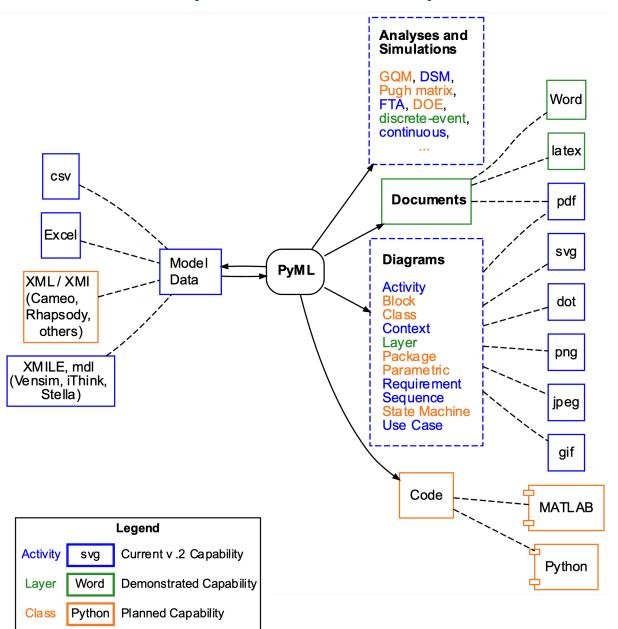
# system model
system_name = "Python Interpreter with PyML"
external_actors = ["User", "OS", "Graphviz"]

# create context diagram
pyml.context_diagram(system_name, external_actors)
```





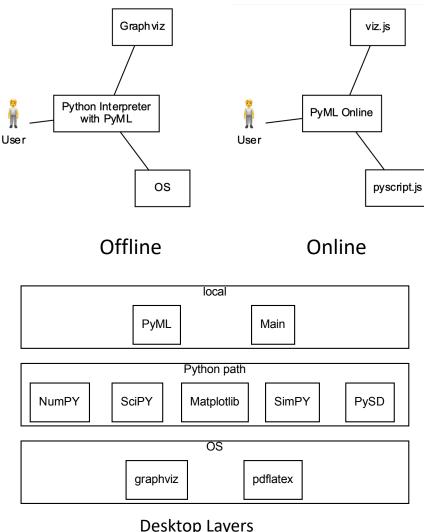
Inputs and Outputs





PyML Context and Architecture

- Desktop usage requires Python version 3.8 or higher.
- Built on top of open-source:
 - Graphviz is required to generate diagrams.
 - The *Matplotlib* package is required for graphical plots.
 - NumPy numerical computing package is used for model analysis and some plotting features.
 - SciPy is a scientific computing library
 - SimPy is a discrete event simulation framework
 - PySD with Pandas for the system dynamics simulation engine
 - *pdflatex* optionally required to compile latex files and generate pdfs





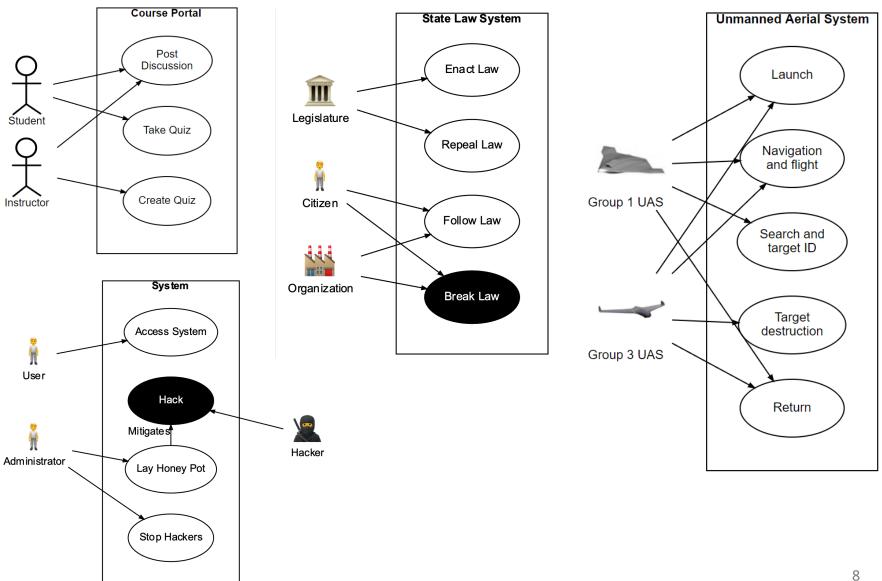
Feature Plans

• V 1.0 release plan is to cover all SysML

Feature	v2 Current	v. 1.0 Planned	v. 1.0+ Planned
SysML			√
Activity diagram	√ (partial)	~	√ simulatable
Package diagram		✓	✓
Use case diagram	~	✓	✓
Requirements diagram	√ (via Tree)	~	✓
Sequence diagram	~	~	√ simulatable
Block diagram		✓	✓
State machine diagram		~	√ simulatable
Parametric diagram		~	✓
Other			
Context diagram	~	~	✓
Qualitative fault tree diagram	~	✓	✓
Quantitative fault tree diagram	✓	~	√ simulatable
Fault tree cutsets	~	~	✓
Class diagram			✓
Layer diagram			✓
Orthogonal Variability Model (OVM) diagram			~
Critical path analysis and diagram	~	~	~
Work Breakdown Structure (WBS) diagram	~	~	✓
Design Structure Matrix (DSM) diagram	✓	~	~
N2 diagram			~
System dynamics modeling and simulation	✓	~	√ diagrams
TBD		~	~

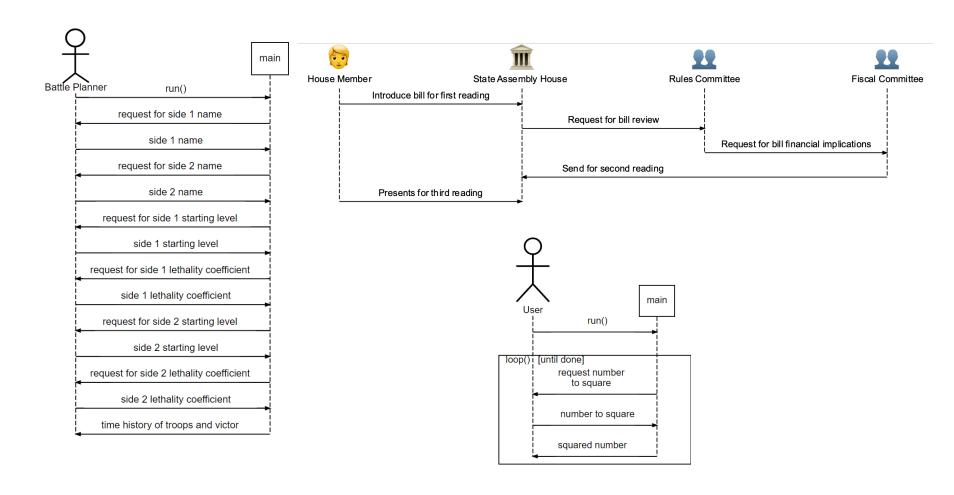


Use Case Diagram Examples





Sequence Modeling Examples



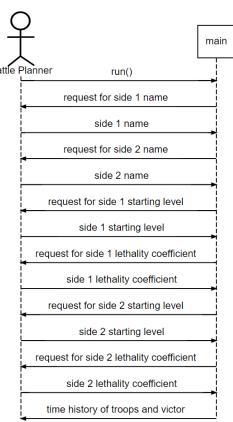


Battle Simulator Inline Model Example

Input

Output

```
import pyml
# system model
system name = "Battle Simulator"
actors = ['Battle Planner']
use_cases = ['Simulate Battle']
interactions = [('Battle Planner', 'Simulate Battle')]
use case relationships = []
                                                                                              Battle Simulator
actions = [
('Battle Planner', 'main', 'run()'),
('main', 'Battle Planner', 'request for side 1 name'),
                                                                                              Simulate Battle
('Battle Planner', 'main', 'side 1 name'),
('main', 'Battle Planner', 'request for side 2 name'),
('Battle Planner', 'main', 'side 2 name'),
('main', 'Battle Planner', 'request for side 1 starting level').
('Battle Planner', 'main', 'side 1 starting level'),
('main', 'Battle Planner', 'request for side 1 lethality coefficient'),
('Battle Planner', 'main', 'side 1 lethality coefficient'),
('main', 'Battle Planner', 'request for side 2 starting level'),
('Battle Planner', 'main', 'side 2 starting level'),
('main', 'Battle Planner', 'request for side 2 lethality coefficient'),
('Battle Planner', 'main', 'side 2 lethality coefficient'),
('main', 'Battle Planner', 'time history of troops and victor'),
# create diagrams
pyml.use_case_diagram(system_name, actors, use_cases, interactions,
use case relationships, filename=system name+'use case diagram.pdf')
pyml.sequence diagram(system name, actions, filename=system name
+'sequence diagram.pdf')
```



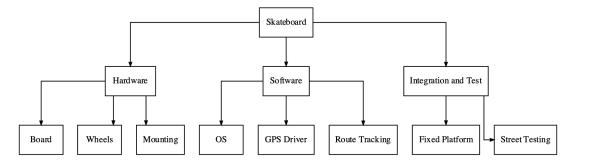


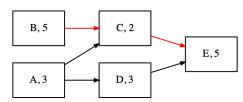
Project Management Modeling (1/2)

```
# project work breakdown structure
wbs_decompositions = [('Skateboard', 'Hardware'), ('Skateboard',
'Software'), ('Skateboard', 'Integration and Test'), ('Hardware',
'Board'), ('Hardware', 'Wheels'), ('Hardware', 'Mounting'),
('Software', 'OS'), ('Software', 'GPS Driver'), ('Software', 'Route
Tracking'), ('Integration and Test', 'Fixed Platform'), ('Integration
and Test', 'Street Testing')]

# create diagram
pyml.wbs_diagram(wbs_decompositions)
```

The critical path is: ['B', 'C', 'E'] for a project duration of 12 days.





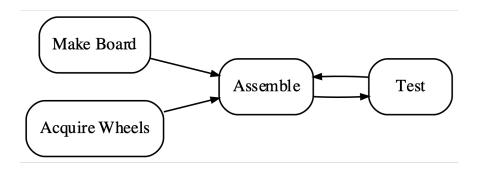


Project Management Modeling (2/2)

```
tasks = ['Make Board', 'Acquire Wheels', 'Assemble', 'Test']
task_dependencies = [('Make Board', 'Assemble'), ('Acquire Wheels',
'Assemble'), ('Assemble', 'Test'), ('Test', 'Assemble')]
pyml.design_structure_matrix(tasks, task_dependencies)
```

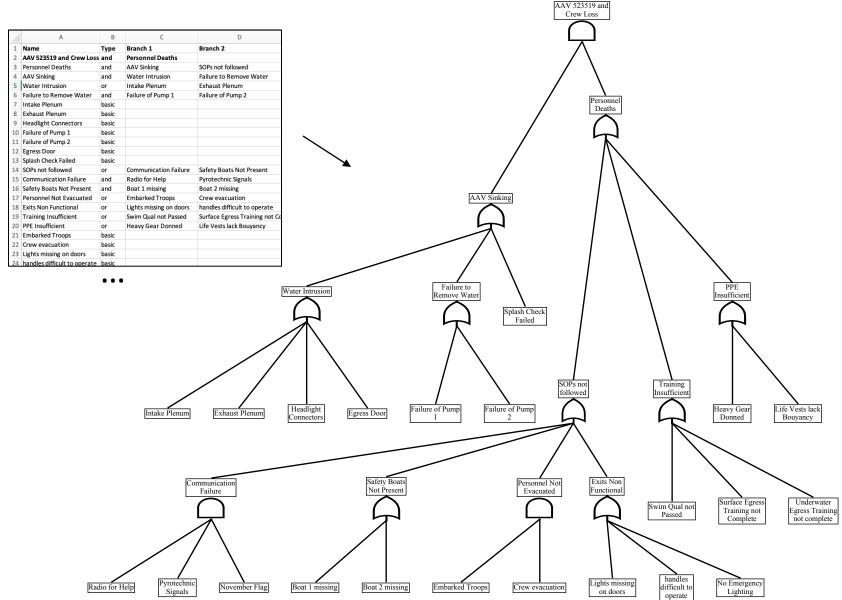
	Make Board	Acquire Wheels	Assemble	Test
Make Board				
Acquire Wheels				
Assemble	X	X		X
Test			X	

pyml.activity_diagram(task_dependencies)





AAV Disaster Fault Tree from Excel





System Dynamics Modeling and Simulation

 Functions provide high level interface for model composition and execution with PySD model reader and simulation engine.

Interoperable with Vensim, iThink/Stella and AnyLogic with xmile model

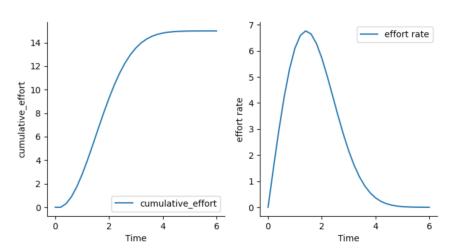
format.

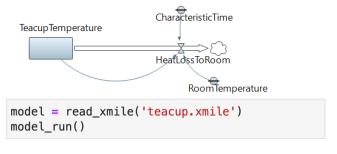
```
# Rayleigh curve staffing model

model_init(start=0, stop=6, dt=.2)

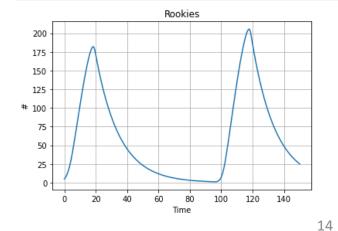
add_stock("cumulative_effort", 0, inflows=["effort rate"])
add_flow("effort rate", "learning_function * (estimated_total_effort - cumulativ add_auxiliary("learning_function", "manpower_buildup_parameter * time")
add_auxiliary("manpower_buildup_parameter", .5)
add_auxiliary("estimated_total_effort", 15)

model_run()
plot_output('cumulative_effort', 'effort rate')
```





```
model = read_vensim('workforce.mdl')
model.run()
plot_output("Rookies")
```

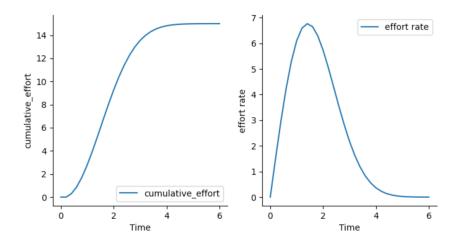




Integrated Requirements and Effort Models

```
requirements = [("ISR", "Communication"),
               ("Communication", "R1.1.1 Mission parameters shall
               ("Communication", "R1.1.2 The UUV shall receive rem
               ("Communication", "R1.1.3 The UUV shall commence it
              ("Communication", "R1.1.4 The UUV shall be capable
               ("Communication", "R1.1.5 The UUV shall indicate th
                                          R1.1.1
                                Mission parameters shall be
                                  uploadable to the UUV
                                          R1.1.2
                               The UUV shall receive remote
                                        commands
                                          R1.1.3
     Communication
                                The UUV shall commence its
                                 mission when commanded
                                          R1.1.4
                               The UUV shall be capable of
                               transmitting data in a host ship
                                     compatible format
                                          R1.1.5
                               The UUV shall indicate that
                               it is ready for recovery
```

```
# effort model
 2 def cosysmo(size, EAF=1):
        return .254*EAF*size**1.06, 1.5*(.254*EAF*size**1.06)**.33
   # effort estimate from requirements
    requirements count = len(requirements)
    effort, schedule = cosysmo(requirements count)
    # Rayleigh curve staffing model
10
11
    model init(start=0, stop=6, dt=.2)
12
13
    add stock("cumulative effort", 0, inflows=["effort rate"])
    add flow("effort rate", "learning function * (estimated total effort - cumulativ
    add auxiliary("learning function", "manpower buildup parameter * time")
    add auxiliary("manpower buildup parameter", .5)
    add auxiliary("estimated total effort", effort)
17
18
19
    model run()
   plot output('cumulative effort', 'effort rate')
```

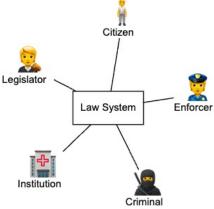


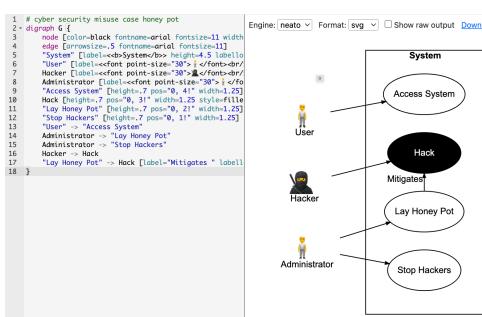


Customization and Shortcuts

- Styling
 - Custom icons with unicode
 - APIs support color options, formatting, word wrap size, and more.
- Shortcuts
 - Use tuples for node fan-in and fan-out connections to alleviate redundancy
- Graphviz online tool enables customization of dot markup at http://pyml.fun/graphviz_online







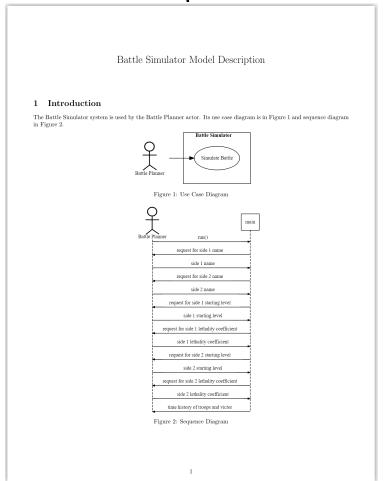


Example Document Generation Including Diagrams

Input

```
from pyml import *
# system model
system name = "Battle Simulator"
actors = ['Battle Planner']
use cases = ['Simulate Battle']
interactions = [('Battle Planner', 'Simulate Battle')]
use_case_relationships = []
actions = [
('Battle Planner', 'main', 'run()'),
('main', 'Battle Planner', 'request for side 1 name'),
('Battle Planner', 'main', 'side 1 name'),
('main', 'Battle Planner', 'request for side 2 name'),
('Battle Planner', 'main', 'side 2 name'),
('main', 'Battle Planner', 'request for x starting level'),
('Battle Planner', 'main', 'x starting level'),
('main', 'Battle Planner', 'request for x lethality coefficient'),
('Battle Planner', 'main', 'x lethality coefficient'),
('main', 'Battle Planner', 'request for y starting level'),
('Battle Planner', 'main', 'y starting level'),
('main', 'Battle Planner', 'request for y lethality coefficient'),
('Battle Planner', 'main', 'y lethality coefficient'),
('main', 'Battle Planner', 'time history of troops and victor'),]
# create diagrams
use case diagram(system name, actors, use cases, interactions,
use case relationships, filename=system name+' use case diagram.pdf')
sequence_diagram(system_name, actors, actions, filename=system_name
+' sequence diagram.pdf')
# generate document
latex_create(system_name + "Model Description")
section("Introduction")
latex string(f"The {system name} system is used by the {list elements(actors)}
actor. Its use case diagram is in Figure \\ref{{Use Case Diagram}} and
sequence diagram in Figure \\ref{{Sequence Diagram}}.")
figure("Use Case Diagram", system name+' use case diagram.pdf')
figure("Sequence Diagram", system name+' sequence diagram.pdf')
latex write(system name + "Model Description.pdf")
```

Output





Initial Online Capabilities

- Test online before downloading
- Use online as-is and manage model files locally

http://pyml.fun/online/sysml.html

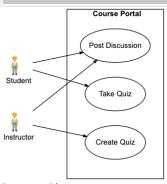
SysML Diagram Scratchpad

Enter Python statements in code cells and click the green run button or hit shift-enter to create diagrams. Additional diagrams can be created in the blank code cells at the end that are automatically generated after runs.

Use Case Diagram

```
# system model
system_name = "Course Portal"
actors = ['Student', 'Instructor']
use_cases = ['Post Discussion', 'Take Quiz', 'Create Quiz']
interactions = [('Student', 'Post Discussion'), ('Instructor', 'Post Discussion'), ('Instructor', 'Create Quiz')]
use_case_relationships = []

# create diagram
use_case_diagram(system_name, actors, use_cases, interactions, use_case_relationships
```



http://pyml.fun/online/system dynamics.html

System Dynamics Demonstrations

These introductory models can be edited and run with the green play buttons. The PyML function names are tentative. See GitHub for the latest PyML library and future examples at pyml.fun.

```
# Battle Simulator using Lanchester's Law for Aimed Fire

model_init(start=0, stop=1.5, dt=.2)

add_stock("x_troops", 1000, outflows=["x_attrition"])

add_flow("x_attrition", "y_troops*y_lethality")

add_auxiliary("x_lethality", .8)

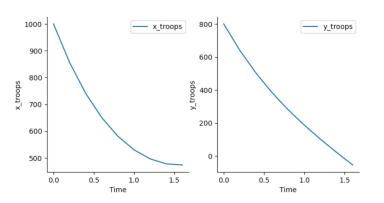
add_stock("y_troops", 800, outflows=["y_attrition"])

add_flow("y_attrition", "x_troops*x_lethality")

add_auxiliary("y_lethality", .9)

model_run()

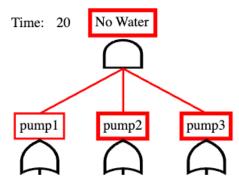
plot_output('x_troops', 'y_troops')
```





Prototyped Upcoming Features

- Activity model diagrams with more node types
- State model diagrams
- Orthogonal variability model diagrams
- Dynamic fault tree simulation





Future Work and Capabilities

- Publish library on Python Package Index (PyPI) software repository
- Additional object-oriented API
 - Foster reuse, adoption and increase sophistication
 - Can alleviate manual bookkeeping across models
- Graphical editor for diagrams in browser using opensource JavaScript
- Natural language extensions
 - E.g., write concise sentences for use case scenario and sequence model interactions using simple grammar rules and keywords
- Code generation from sequence and activity models
- See http://pyml.fun for more information.



References

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- Python Modeling Library (PyML) Repository, https://github.com/madachy/PyML, Accessed December 2, 2022
- sysml.org, SysML Open Source Project What is SysML? Who created SysML? https://sysml.org/, Accessed December 7, 2021
- R. Giachetti. "Digital Engineering." in SEBoK Editorial Board. 2021. The Guide to the Systems Engineering Body of Knowledge (SEBoK), v. 2.5. Hoboken, NJ: The Trustees of the Stevens Institute of Technology, https://www.sebokwiki.org/wiki/Digital_Engineering, Accessed December 7, 2021
- U.S. Department of Defense CIO, DoD Open Source Software FAQ, https://dodcio.defense.gov/open-source-software-faq/, Accessed December 7, 2021



Backup



Available Functions

```
# Version 0.2 function calls
# SysML and related
context_diagram(system, external_systems, filename=None, format='svg', engine='neato')
activity_diagram(element_dependencies, filename=None, format='svg')
use case diagram(system name, actors, use cases, interactions, use case relationships,
filename=None, format='svg')
sequence diagram(system_name, actors, objects, actions, filename=None, format='svg')
# project modeling
critical_path_diagram(tasks, task_dependencies, filename=None, format='svg')
design structure matrix(elements, element dependencies, filename=None, format='svg')
wbs diagram(decompositions, filename=None, format='svg', rankdir='TB')
# generic
tree(element_dependencies, filename=None, format='svg')
# fault trees
fault_tree_diagram(ft, filename=None, format='svg')
read_fault_tree_excel(filename)
draw_fault_tree_diagram_quantitative(ft, filename=None, format='svg'):
fault tree cutsets(fault tree)
# system dynamics
model init()
add_stock()
add_flow()
add auxiliary()
model_run()
plot output()
```



Example API Specifications

pyml.sequence_diagram

pyml.sequence_diagram(system_name, actors, objects, actions, filename=None, format='svg')

Draw a sequence diagram.

Parameters:: system_name: string

The name of the system to label the diagram.

actors : list of strings

Names of the outside actors that participate in the activity sequence in a list.

objects: list of strings

Names of the system objects that participate in the activity sequence in a list.

actions : list of tuples

A chronologically ordered list describing the sequence of actions to be drawn. Each action is a tuple containing the action source, target and action name (or data/control passed) in the form ("source", "target", "action name") indicating a labeled horizontal arrow drawn between them.

filename : string, optional

A filename for the output not including a filename extension. The extension will specified by the format parameter.

format : string, optional

The file format of the graphic output. Note that bitmap formats (png, bmp, or jpeg) will not be as sharp as the default svg vector format and most particularly when magnified.

Returns:: g : graph object view

Save the graph source code to file, and open the rendered result in its default viewing application. PyML calls the Graphviz API for this.



Example Modeler Scenario for Roundtrip Digital Engineering

- Joe is developing a system architecture and wants to make changes for integrated models in one
 place with no extra manual steps to recompute analyses, regenerate all model artifacts for other
 stakeholders, and communicate important change impacts. PyML library functions are used in
 the modeling and documentation. All model data and analysis programs must be configuration
 controlled to adhere to a common baseline.
- The distributions of some system parameters need to be revised that will affect requirements, performance and cost models. Simulations assess the system availability and reliability, perform a hazard analysis, estimate cost, and the Measures of Effectiveness (MOEs) are aggregated in a weighted criteria matrix.
- He accesses the shared project repository on GitHub and updates the parameters in a main configuration file. He commits the changes back into GitHub.
- He wants the changes to trigger a common script that reconciles the models, recomputes all simulations with the updated parameter values, and produces an updated set of documents online for other stakeholders. All affected visualizations need to be regenerated and inserted into iterative project documents. The scripts need to call the requisite programs for analysis and documentation using the library functions with updated model data.
- Errors and warning notices are to be provided for any broken or inconsistent models. E.g., a performance or cost threshold is not being met, or a previously working simulation model fails to execute properly with the new parameter values.
- He wants the stakeholders who specified thresholds for affected MOEs to automatically get notice. He expects this will occur if the requirements data contains the source of each requirement.



DoD Business Case

- Anecdotal evidence indicates the Pareto Law holds for costly MBSE vendor tools: about 90% of users use only 10% of their features.
- Open source software is fully permissible and encouraged in the DoD
- DoD Open Source Software FAQ:
 - https://dodcio.defense.gov/open-source-software-faq/